

PUMA VTS1214 / 1620

Large Vertical Turning Center with RAM Head Spindle



PUMA VTS1214/1620

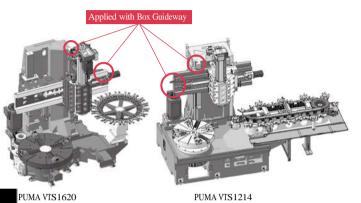
With its large capacity and heavy duty machining capability,
The PUMA VTS series provides excellent productivity for large workpieces



Features

Robust Structure

The PUMA VTS series provides optimum durability by including box guideway construction to all linear axes. The large diameter cross taper roller bearing used in the spindle construction provides high rigidity and accuracy for heavy duty machining applications





PUMA VTS 1620

PUMA VTS1620

ghest Cutting Capacity among Competitors Provides maximum workpiece size capacity

Max. Turning diameter PUMA VTS1620

 \emptyset 2000 mm (78.7 inch)

PUMA VTS1214 Ø 1350 mm (53.1 inch)



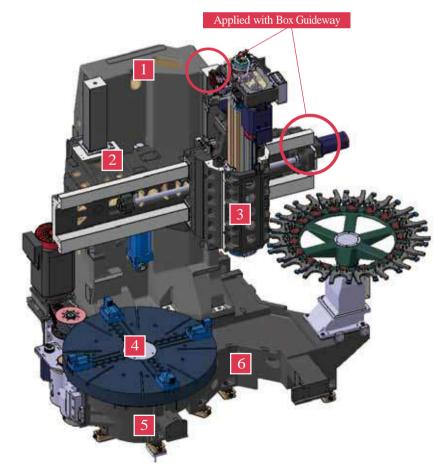


Robust Mechanical Construction PUMA VTS 1620 series

The PUMA VTS1620M series provides extended durability and stable accuracy by implementing a large diameter cross roller bearing for the spindle and box guideways for the linear axes.

PUMA VTS1620 series

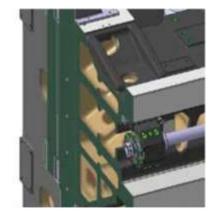
Machine Construction



Model: PUMA VTS1620 Core Machine



A highly rigid X-type cast Meehanite column structure reduces deflection and ensures optimum cutting performance.



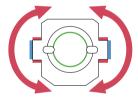
Deflection is avoided by the high rigidity crossrail and ram carriage construction.





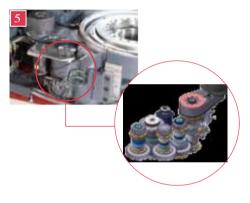
Large square cross-section

 $308 \times 250 \text{ mm}$ $(12.1 \times 9.8 \text{ inch})$



Wide ram guide for high torque

Ram deformation minimized by enlarged guideway design enabling heavy duty cutting.



Applied with powerful helical gears to guarantee a long life. The VTS1620M is applied with a zero backlash system to realize accurate Caxis control.



Designed with large diameter cross taper roller bearing featuring high rigidity in both radial and axial directions. The gears are capable of transmitting high cutting forces.

Max. Table motor

Max. Table torque

Max. Table speed

 $45 \{60\} \, kW = 19875 \{24380\} \, N \cdot m = 250 \, r / min$ (60.3 {80.5} Hp) (14667.8 {17992.4} ft·lb)

{ } : Option

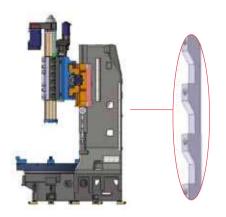


Designed in a base structure that provides a stable cutting performance to the table and carriage, using an X rib structure Meehanite casting.

Large Workpiece Capacity and Processing Capability

Crossrail Fixed Positions

The 4 position step block is provided to fix the W axis position of the crossrail, and in combination with a positioning pin, maintains a high level of positioning control.

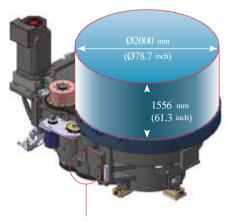


Crossrail fixed positions

 $200 \text{ mm} \times 4 \text{ steps} = 800 \text{ mm}$ (7.9 inch) (31.5 inch)

(actuated by hydraulic cylinder)

Axis Travel



The built in 2-step gearbox provides a stable high torque drive

Max. Turning diameter Ø2000 mm Z-axis 960 mm

(78.7 inch) (37.8 inch)

 $\text{Max. Turning height} \qquad 1556 \quad \text{mm} \qquad \text{W-axis} \quad 800 \quad \text{mm}$

(61.3 inch) (31.5 inch)

Max. Allowable load 10000 kg X-axis 1727 mm (22045.9 lb) (68.0 inch)

ATC Magazine



Driving system Servo motor

No. of tool stations 18 {24} stations

Max. Tool length in 450 mm (17.7 inch)

Z-axis (Static tool)

350 mm (13.8 inch) (BT50/DIN 50 rotating tool)

Max. Tool weight 50 Kg (110.2 lb)/tool

{ } : Option

C-axis Table



C-Axis Servo Motor VTS 1620(M)

Max. Power and 4 kW (5.4 Hp)

torque 26400 N·m (19483.2 ft·lb)

C-axis feedrate 900 deg/min

(travel 360°, 0.001° control)

Servo controlled c-axis table enables milling, drilling and tapping with excellent rotational accuracy and user satisfaction.

Table Motor Power - Torque



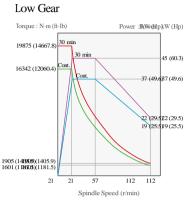
Max. Table motor & torque

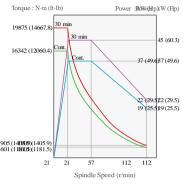
45 kW 19875 N·m (60.3 Hp) (14667.8 ft·lb)

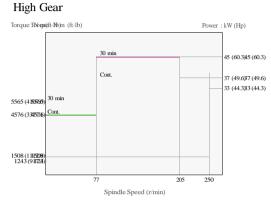
Max. Table motor & torque opt.



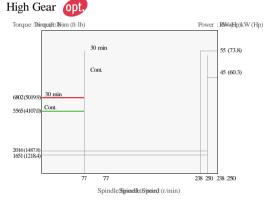
(80.5 Hp) (17992.4 ft·lb)











Ram Rotary Spindle

(common for PUMA VTS1214M/VTS1620M)

Max. Rotary tool power

18.5 kW 15 kW opt. (20.1 Hp) (24.8 Hp)

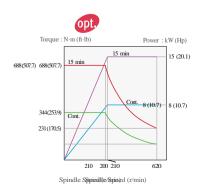
Max. Rotary tool torque

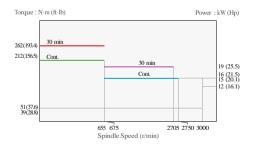
(193.4 ft·lb) (507.0 ft·lb)

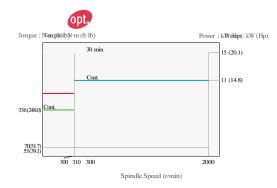
Max. Rotary tool speed

3000 r/min

2000 r/min



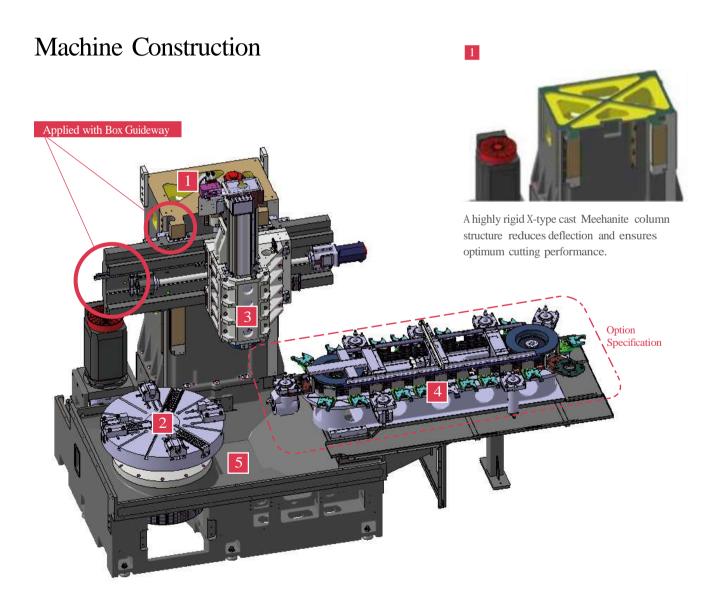




Robust Mechanical Construction PUMA VTS 1214 series

The PUMA VTS1214 series has minimized heat and vibration emissions using a separable-type gearbox, and it exhibits a high rigidity in heavy duty cutting using large bearings.

PUMA VTS1214 series



Model: PUMA VTS 1214 Core Machine



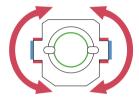


Vibration and heat generation at the spindle are minimized with a belt-driven, detachable gearbox. Cutting capacity and safety are enhanced with large diameter bearings.



Ram deformation is minimized with an enlarged guideway. A wide ram guide enables heavy duty cutting. Large square cross-section

 $308 \times 250 \text{ mm} \atop \text{(12.1} \times 9.8 \text{ inch)}$



Wide ram guide corresponding to high torque



24 tool magazines are reinforced with a rigid rib structure for maximum stability.

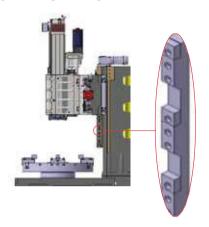


The column and spindle are rigidly supported using a grid-type, rib structure Meehanite cast. Chips can be easily discharged through the sloped top surface.

Cutting Capacity

Crossrail Fixed Positions

The 4 position step block is provided to fix the W axis position of the crossrail, and in combination with a positioning pin, maintains a high level of positioning control.

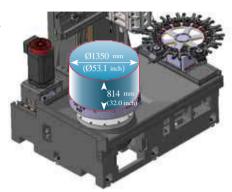


Crossrail fixed positions

 $150 \text{ mm} \times 4 \text{ steps} = 600 \text{ mm}$ (5.9 inch)

(Geared motor control type)

Axis Travel



Max Turning diameter Ø1350 mm (53.1 inch)

Hydraulic chuck 40 " {50 "}

Swing over bed 1400 mm (55.1 inch)

Max. Workpiece length 814 mm (32.0 inch)

Max. Workpiece weight 4000 kg (8818.4 lb)

(Including chuck)

Z-axis W-axis X-axis

800 mm (31.5 inch) 600 mm (23.6 inch) 1450 mm (57.1 inch)

ATC Magazine



Driving system Servo motor

No. of tool stations 15 {24} stations

Max. Tool length 450 mm (17.7 inch) (Static tool)

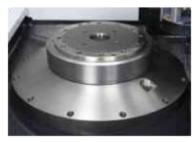
350 mm (13.8 inch) (BT50/DIN 50 rotating tool)

Max. Tool weight 50 Kg (110.2 lb)/tool

 $\{\ \}$: Option

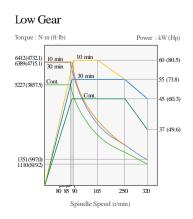
{ } : Option

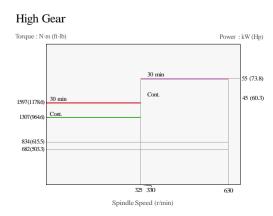
Table Motor Power - Torque



Max. Table Motor & Torque

60 kW (80.5 Hp) 6412 N·m (4732.1 ft·lb)





Optional Equipment and Chip Disposal

Optional Equipment







Linear scale



Auto tool setter



Oil mist collector (except PUMA VTS1620)



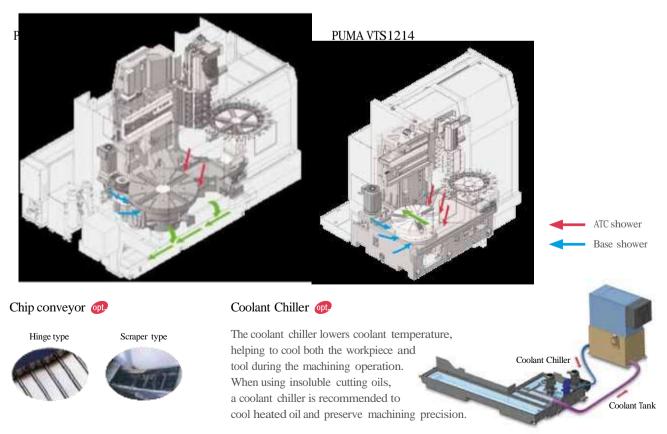
Oil skimmer



Automatic pallet changer

Easy Chip Discharge Design

Chips falling off to the left and right are collected in a chip pan and removed by a chip conveyor.



Tooling System

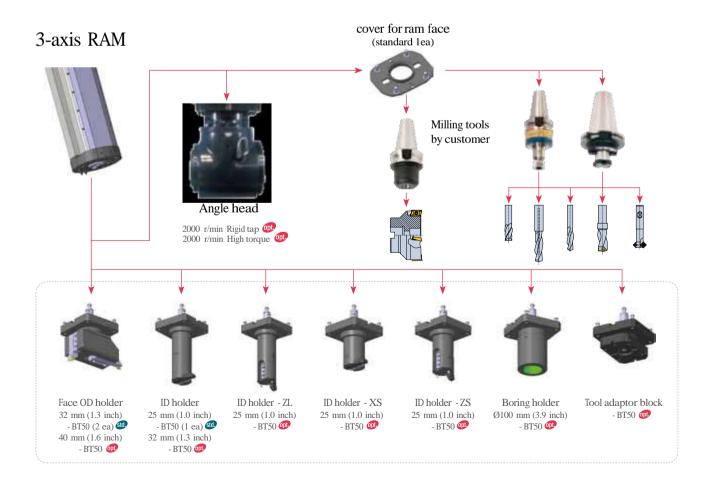
40 mm (1.6 inch)

- BT50 🐽

32 mm (1.3 inch)

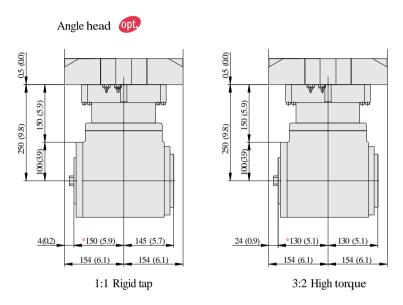
- BT50 opt

2-axis RAM Unit: mm (inch) Tool adaptor block - BT50 opt Face OD holder ID holder ID holder - ZL ID holder - XS ID holder - ZS Boring holder Ø100 mm (3.9 inch) - BT50 32 mm (1.3 inch) - BT50 std 25 mm (1.0 inch) 25 mm (1.0 inch) 25 mm (1.0 inch) - BT50 25 mm (1.0 inch) - BT50 - BT50 opp -BT50 (1 ea) std

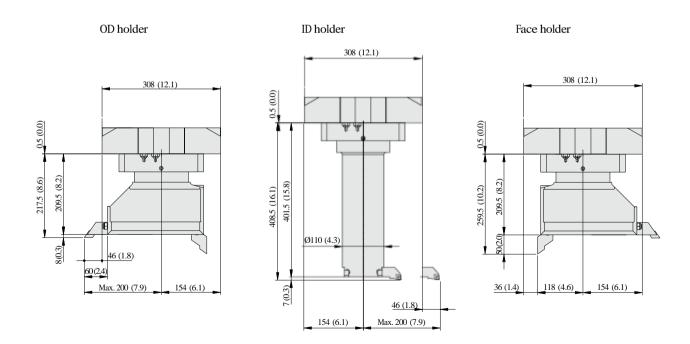


Tool Holder Dimentions

Unit: mm (inch)



 $\ensuremath{^{*}}\xspace$ If the magazine is attached, tools are need to separate.



Easy CNC Set-up and EOP

Easy Set-up



Operating console

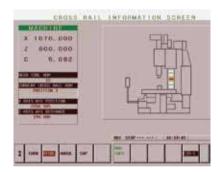
- Doosan-Fanuc i series
- 2 10.4" color TFT LCD Monitor Various alarm messages indicating errors from the machine and controller will be displayed on the 10.4" LCD screen, enhancing the operator's convenience.
- O PCMCIA Card
- 4 USB Port (only DOOSAN Fanuc i seres)
- 5 Ethernet function (embedded)
- 6 Swivel-type Operating Consol
- Part program storage 1280m(512kB)

ATC Guidance

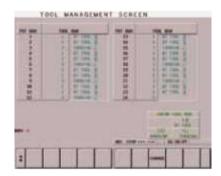
ATC guidance main screen display



Guidance screen for ATC tool change

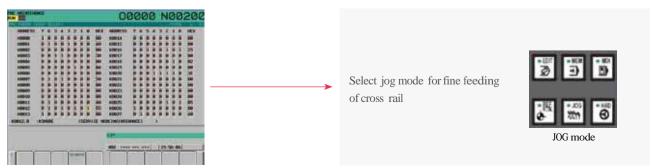


Tool holder information screen



Cross Rail Manual Fine Feeding

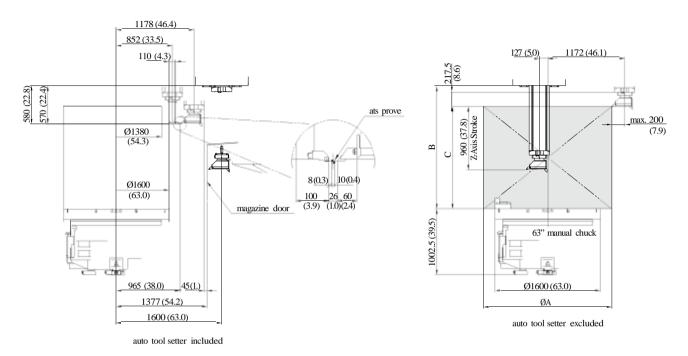
Fine feeding for the cross rail service and adjustment



Working Range

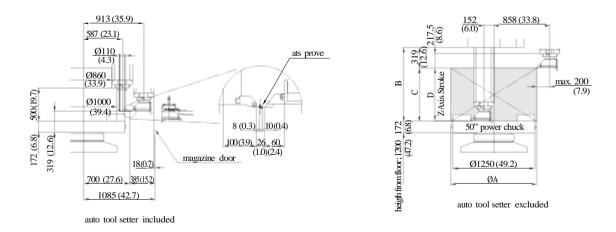
PUMA VTS1620 / VTS1620M

Unit: mm (inch)



-		W-Axis 1	Step; 0	W-Axis 2	Step; 200	W-Axis 3	Step; 400	W-Axis 4	Step; 600	W-Axis 5	Step; 800
	A	В	С	В	С	В	С	В	С	В	С
Face Tool Holder	2000 (78.7)		716 (28.2)		916 (36.1)		1116 (43.9)		1316 (51.8)		1516 (59.7)
OD Tool Holder	1940 (76.4)	968 (38.1)	756 (29.8)	1168 (46.0)	956 (37.6)	1468 (57.8)	1156 (45.5)	1668 (65.7)	1356 (53.4)	1868 (73.5)	1556 (61.3)
X-Long ID Tool Holder	2000 (78.7)		567 (22.3)		767 (30.2)		967 (38.1)		1167 (45.9)		1367 (53.8)

PUMA VTS1214 / VTS1214M



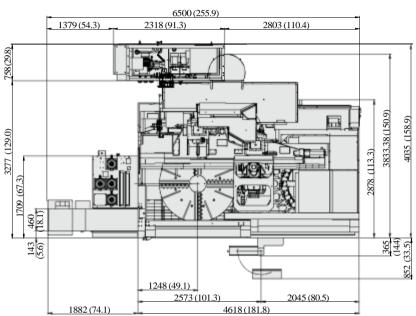
·		W-A	xis 1 Step; 0	mm	W-Axis 2 S	Step; 150 mn	(5.9 inch)	W-Axis 3 St	ep; 300 mm	(11.8 inch)	W-Axis 4 St	ep; 450 mm	(17.7 inch)	W-Axis 5 St	ep;600 mm	(23.6 inch)
	A	В	C	D	В	C	D	В	C	D	В	С	D	В	С	D
Face Tool Holder	1350(53.1)		172 (6.8)	2.50	****	322(12.7)	#00		472(18.6)	450	0.00	622 (24.5)	000	4400	772 (30.4)	
OD Tool Holder	1316(51.8)	533 (21.0)	214 (8.4)	350 (13.8)	683 (26,9)	364(14.3)	500 (19.7)	833 (32.8)	514(20.2)	650 (25.6)	983 (38.7)	664(26.1)	800 (31.5)	1133	814(32.0)	800
X-Long ID Tool Holder	1350(53.1)	(21.0)	23 (0.9)	(13.0)	(20.7)	173 (6.8)	(1).7)	(32.6)	323 (12.7)	(23.0)	(36.7)	473 (18.6)	(31.3)	(44.0)	623 (24.5)	(31.3)

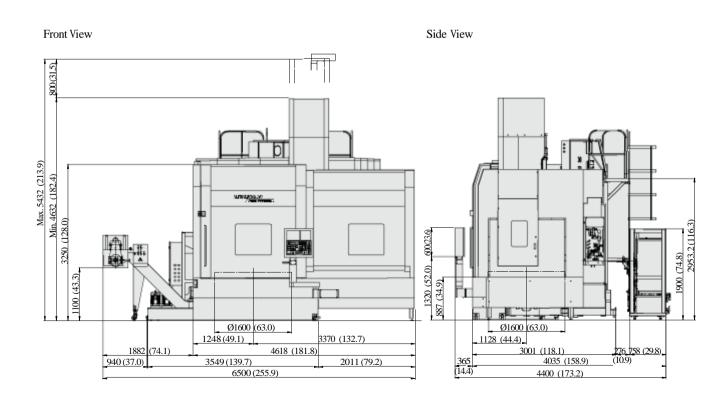
External Dimension

PUMA VTS1620 / VTS1620M

Unit: mm (inch)



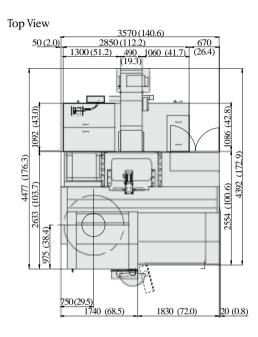




External Dimension

PUMA VTS1214 / VTS1214M

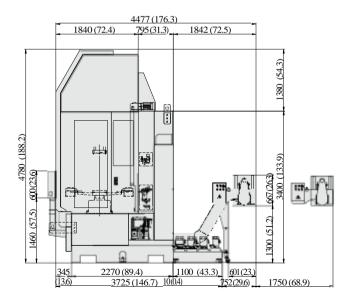
Unit: mm (inch)



Front View

3590 (141.3) 3570 (140.6) 20 (0.8) (0.8) (0.8) (0.8) (0.8) (0.8) (0.8) (0.8) (0.8) (0.8) (0.8) (0.8) (0.8)

Side View



Machine Specifications

	Features		Unit	PUMA VTS 1620	PUMA VTS1620M	PUMA VTS1214	PUMA VTS1214M*
	Swing over	r bed	mm (inch)	2000	(78.7)	1400	(55.1)
	Swing over	r cross rail	mm (inch)	600 ((23.6)	750	(29.5)
Capacity	Max. Turni	ng diameter	mm (inch)	2000	(78.7)	1350	(53.1)
	Max. Turning height Max. Turning weight		mm (inch)	1556	(61.3)	814	(32.0)
			kg (lb)	10000 (22045.9)		4000 (8818.4)	
		X-axis (To left from table center)	mm (inch) 127 (5.0)		152 (6.0)		
Travels Travel distance	(To right from table center)	mm (inch)	1600	(63.0)	1298	(51.1)	
	Travel	Z-axis	mm (inch)	960 (37.8)		800 (31.5)	
	distance	C-axis	deg	-	360	-	360
		W-axis	mm (inch)	800 (31.5)	600	(23.6)
	Vovic		m/min		2		12
Feedrates	Rapid Traverse	Z-axis	m/min	1	2		12
recurates	Rate	C-axis	deg/min	1.	900		900
	Ram size	C-axis	mm (inch)	209 × 250		208 × 250	
Ram		ah hala inaida diamatan	mm (inch)	308 × 250 (12.1 × 9.8)		308 × 250 (12.1 × 9.8)	
	Min. through hole inside diameter		r/min	320 (12.6) 250		320 (12.6)	
Table	Max. Spindle speed Table size Spindle begring diameter		1/111111			630 1000 (40")	
Table			mm (inch)	1600 (63")			(9.4)
	Spindle bearing diameter		` ′	ì ′		- 240	` '
	Max. rotar	y tool spindle torque	ea	-	262 {687}	-	262 {687}
Rotary Tool	Max. roatr	x. roatry tool spindle speed		-	3000 {2000} (118.1 {78.7})	-	3000 {2000} (118.1 {78.7})
	Rotary tool bearing diameter		mm (inch)		100 (3.9)		100 (3.9)
	Tool storag	C .	stations	18 {24}		15 {24}	
Tool	1001310145	Face OD	Stations	32	× 32		×32
magazine	Tool size	ID			× 25		× 25
	Table moto		kW (Hp)	45 (60.3) / 37.5 (50	0.3) (30min/cont.)	60 (80.5) / 55 (73.8) / 45 (60.3)
Motors	Rotary tool motor power		kW (Hp)	- - -	(3) (10min/cont.) 18.5 (24.8) / 15 (20.1) (30min/cont.) {15(20.1)/11(14.8) (30min/cont.)}	(10min/30	0min/cont.) 18.5 (24.8) / 15 (20.1) (30min/cont.) {15 (20.1) / 11 (14.8) (30min/cont.)}
Power	Electric power supply(rated capacity)		kVA	90	100	90	110
	Height		mm (inch)	5639 ((222.0)	4820	(189.8)
Machine	Width		mm (inch)		204.7 × 135.9)		
Dimensions	Weight		\ /		31000 (68342.3)		1
NC CONTRO	U					series / Fanue 32i	

^{*} For machining accuracy of X/C axes contouring, please contact Doosan.

 $\{\quad\}: Option$

Standard Feature

- 3 jaws hydraulic chuck (VTS1214/M)
- 4 jaws manual chuck (VTS1620/M)
- ATC shower coolant
- · Bed shower coolant
- Column ladder and rail (VTS1620/M)
- Crossrail positioning unit
- Hydraulic unit
- Leveling bolts and plates

- Lubricant supplier
- Machine installation parts
- M code program (Drive vertical crossrail)
- Ram air blast
- Ram shower coolant
- Splash guard
- Standard tool holder
- Table cooling system (VTS1620/M)
- Tool clamp air seating checker

Optional Feature

- 50" hydraulic chuck (VTS1214/M)
- 50" combination chuck (VTS1214/M)
- 63" combination chuck (VTS1620)
- 70 bar coolant
- Air conditioner
- Automatic front door
- Auto tool setter
- Chip bucket, chip conveyor

- Coolant gun
- Linear scale (X, Z-axis)
- Line filter for coolant
- Mist collector (VTS1214/M)
- Oil Skimmer (belt type)
- Parts probe
- Signal tower
- Special chuck

[•] The specifications and information above-mentioned may be changed without prior notice.

[•] For more details, please contact Doosan

NC Unit Specifications

DOOSAN Fanuc i series

Standard Specifications

AXES CONTROL	
- Controlled axes X, Z, C (X, Z, C	C. E - VT
- Simultaneously controllable axes	3 axes
- Axis control by PMC	
- Backlash compensation 0 ~ ± 9999) pulses
- Backlash compensation for each rapid	1
traverse and cutting feed	
- Chamfering on/off	
- Cs contouring control	
- HRV2 control	
- Inch / Metric conversion	
- Increment system 1/10	
0.0001 / 0.00001 m	nm/inch
- Interlock All axes / ea	ch axis
- Least input command 0.001 / 0.0001 n	nm/inch
- Machine lock All axes / ea	ch axis
- Overtravel	
- Overtraver - Position switch - Stored stroke check 1	
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3	
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION	
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3	
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory)	face
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register	face
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter	
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1	
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed	0, X100
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed - Manual handle feed	0, X100
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed - Manual handle feed	0, X100
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed - Manual handle feed - Refernce position setting without do	0, X100
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed - Manual handle feed - Refernce position setting without de - Wrong operation prevention	0, X100 1 unit
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed XI, XI - JOG feed - Manual handle feed - Refernce position setting without de- Wrong operation prevention INTERPOLATION FUNCTIONS - 1st. reference position return Manu	0, X100 1 unit
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed - Manual handle feed - Refernce position setting without dc - Wrong operation prevention INTERPOLATION FUNCTIONS - 1st. reference position return Manu - 2nd. reference position return	0, X100 1 unit og 1al, G28 G30
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed - Manual handle feed - Refernce position setting without dc - Wrong operation prevention INTERPOLATION FUNCTIONS - 1st. reference position return Manual - 3rd/4th. reference position return	1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 2 unit 3 unit 3 unit 6 unit 6 unit 6 unit 7 unit 7 unit 8 unit 8 unit 8 unit 9 unit 0
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed XI, XI - JOG feed - Manual handle feed - Refernce position setting without de - Wrong operation prevention INTERPOLATION FUNCTIONS - Ist, reference position return - 2nd, reference position return - Circular interpolation	1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 2 unit 3 unit 3 unit 6 unit 6 unit 6 unit 7 unit 7 unit 8 unit 8 unit 8 unit 9 unit 0
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher inter is required) - Handle incremental feed X1, X1 - JOG feed - Manual handle feed - Refernce position setting without dc - Wrong operation prevention INTERPOLATION FUNCTIONS - 1st, reference position return - 2nd, reference position return - 3rd/4th, reference position return - Circular interpolation - Continuous threading	1 unit og 1 unit
- Position switch - Stored stroke check 1 - Stored stroke check 2, 3 OPERATION - Automatic operation(memory) - Buffer register - DNC operation(Reader/puncher interis required) - Handle incremental feed XI, XI - JOG feed - Manual handle feed - Refernce position setting without de - Wrong operation prevention INTERPOLATION FUNCTIONS - Ist, reference position return - 2nd, reference position return - Circular interpolation	0, X100 1 unit

- Polar coordinate interpolation	
- Positioning	G00
- Reference position return check	G27
 Thread cutting / Synchronous cutti 	ng
FEED FUNCTION	
- Automatic acceleration / decelerati	ion
- Cutting feedrate clamp	
- Feedrate override (10% unit)	
- Jog feed override (10% unit) 0 - 2000	mm/min
- Override cancel	
	5, 100 %
- Tangential speed constant control	
ATTIMITATIVE CONTROL E CONTROL ET DE	OTTON
AUXILIARY / SPINDLE SPEED FUN	CHON
- Constant surface speed control	
- High speed M/S/T interface	
- Spindle orientation	
PROGRAM INPUT	
- Absolute/incremental programmin	
 Addition of custom macro common 	
 Automatic coordinate system settir 	ıg
- Canned cycle for drilling / Turning	
- Circular interpolation by R program	
- Coordinate system setting	G50
- Custom macro	
- Decimal point programming/	
- Diameter/radius programming (X a	
- Direct drawing dimension program	ming
- Direct of coordinate system shift	
- G code system A/B/C	
- Input unit 10 time multiply	
- Maximum program dimension	±9 digit
- Multiple repetitive canned cycle G	370 - G76
- Multiple repetitive canned cycle II	
- Optional block skip	1 piece
- Optional block skip (Soft operator's	
	9 pieces

- Pocket calculator type decimal point programming

- Override cancel - Rapid traverse override

G17, G18, G19

F0, 25, 100 %

- Program number	O4 digit
- Program stop / end (M00.	
- Programmable data inpu	
- SUB program call	4 folds nested
- Tape code : ISO / EIA auto	
	EIA RS422/ISO840
- Tape format for FANUC Se	
- Work coordinate system	G52 - G59
TOOL FUNCTION / TOOL	COMPENSATION
- Automatic tool offset	
- Direct input of offset valu	ue measured B
- Extended tool life manage	gement
- T - code function	T2+2 digits
- Tool geometry / wear con	mpensation
- Tool life management	*
- Tool nose radius comper	nsation
- Tool offset	G43, G44, G49
- Tool offset pairs	64 pairs
EDITING OPERATION	
EDITING OF EXALION	
- Extended part program e	diting
 Extended part program e Number of registered pro 	ograms 400 ea
 Extended part program e Number of registered program storage length 	ograms 400 ea
 Extended part program e Number of registered pro 	ograms 400 ea
 Extended part program e Number of registered program storage length 	ograms 400 ea th 1280 (512KB) m
Extended part program e Number of registered pro Part program storage lengt Program protect	ograms 400 ea th 1280 (512KB) m
- Extended part program e - Number of registered pro- - Part program storage lengt- - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display	ograms 400 ea th 1280 (512KB) m Y isplay
- Extended part program e - Number of registered pro - Part program storage lenge - Program protect SETTING AND DISPLA - Actual cutting feedrate d	ograms 400 ea th 1280 (512KB) m Y isplay
- Extended part program e - Number of registered pro- - Part program storage lengt- - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display	ograms 400 ea th 1280 (512KB) m Y isplay nch for each group
Extended part program e - Number of registered pre - Part program storage lengi - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and pu - Display of spindle speed anc - Multi-language display	ograms 400 ea th 1280 (512KB) m Y isplay nch for each group 1T code at all screens
- Extended part program e - Number of registered pre - Part program storage lengt - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and put - Display of spindle speed and	ograms 400 ea th 1280 (512KB) m Y isplay nch for each group 1T code at all screens
Extended part program e - Number of registered pre - Part program storage lengi - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and pu - Display of spindle speed anc - Multi-language display	ograms 400 ea th 1280 (512KB) m Y isplay nch for each group 1T code at all screens.
- Extended part program e - Number of registered pre - Part program storage lengi - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and pu - Display of spindle speed an - Multi-language display - Operating monitor scree	ograms 400 ea th 1280 (512KB) ir Y isplay neth for each group 11 code at all screens n splay
- Extended part program e - Number of registered pro - Part program storage lengt - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and pu - Display of spindle speed and - Multi-language display - Operating monitor scree - Parameter setting and di	ograms 400 ea th 1280 (512KB) m Y isplay neth for each group 11 code at all screens n splay 31 characters
Extended part program e - Number of registered pre - Part program storage lengi - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and pu - Display of spindle speed ane - Multi-language display - Operating monitor scree Parameter setting and di - Program name display	ograms 400 ea th 1280 (512KB) m Y isplay neth for each group 11 code at all screens n splay 31 characters
- Extended part program e - Number of registered pre - Part program storage lengi - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and pu - Display of spindle speed ane - Multi-language display - Operating monitor scree - Parameter setting and di - Program name display - Run hours / parts count	ograms 400 ea th 1280 (512KB) m Y isplay neth for each group 11 code at all screens n splay 31 characters
- Extended part program e - Number of registered pre - Part program storage lengt - Program protect SETTING AND DISPLA - Actual cutting feedrate d - Alarm history display - Directory display and pu - Display of spindle speed anc - Multi-language display - Operating monitor scree - Parameter setting and di - Program name display - Run hours / parts count - Self-diagnosis function - Self-diagnosis function	ograms 400 ea th 1280 (512KB) m Y isplay neth for each group 11 code at all screens n splay 31 characters

- Cycle start and lamp

- Tool offset

 Feed hold and lamp NC and servo ready 	
	front of LCD display uni
- PMC system	0iD-PM
- Reset / rewind	
OPERATION GUID.	ANCE FUNCTION
- eZ Guide i	Only 10.4 Color LC
- Manual Guide 0i	Only 8.4 Color LC
INTERFACE FUNCT	TON
- Ethernet function	
Optional Spec	ifications
	meations
AXIS CONTROL	
	nsion(total) Max. 4 axe
 Simultaneous control 	lled axes expansion(total
	Max. 4 axe
OTHERS	
	(Only Lynx220M/300M
- 10.4" Color TFT LCD - Advanced preview of	control
- 10.4" Color TFT LCD - Advanced preview of	control
- 10.4" Color TFT LCD - Advanced preview of - Dynamic graphic di	control splay Only Lynx-serie
- 10.4" Color TFT LCD - Advanced preview of Dynamic graphic di - Fast ethernet / Data - Helical interpolation	control splay Only Lynx-serie a server n
- 10.4" Color TFT LCD - Advanced preview of Dynamic graphic di - Fast ethernet / Data - Helical interpolation - High speed skip fur	control splay Only Lynx-serie a server n action
- 10.4" Color TFT LCD - Advanced preview of - Dynamic graphic di - Fast ethernet / Data - Helical interpolation - High speed skip fur - Manual handle inte	control splay Only Lynx-serie a server n action rruption
- 10.4" Color TFT LCD - Advanced preview of Dynamic graphic di - Fast ethernet / Data - Helical interpolation - High speed skip fur - Manual handle inte	control splay Only Lynx-serie a server n notion rruption d 2 unit
- 10.4" Color TFT LCD - Advanced preview of Dynamic graphic di - Fast ethernet / Data - Helical interpolation - High speed skip fur - Manual handle inte	control splay Only Lynx-serie a server n n noction rruption d 2 unit
- 10.4" Color TFT LCD - Advanced preview of Dynamic graphic di - Fast ethernet / Data - Helical interpolation - High speed skip fur - Manual handle inte - Manual handle feed - Number of tool offs	control splay Only Lynx-serie server n nction rruption d 2 unit et 99 pair
-10.4" Color TFI LCD -Advanced preview - Dynamic graphic di - Fast ethernet / Data - Helical interpolation - High speed skip fur - Manual handle feee - Number of tool offs ROBOT INTERFACI - Robot interface with	control splay Only Lynx-serie server n nction rruption 1 2 unit et 99 pair E n PMC I/O module
-10.4" Color TFI LCD - Advanced preview Dynamic graphic di - Fast ethernet / Data - Helical interpolatio - High speed skip fur - Manual handle inte - Manual handle feee - Number of tool offs ROBOT INTERFACI - Robot interface will - (Hardware between	control splay Only Lynx-serie splay Only Lynx-serie server n tection rruption d 2 unit et 99 pair E n PMC I/O module 1 PMC I/O mudules)
- Advanced preview of Dynamic graphic di Fast ethernet / Dats - Helical interpolation - High speed skip fur - Manual handle inter - Manual handle feet - Number of tool offs - ROBOT INTERFACI - Robot interface with	control splay Only Lynx-serie splay Only Lynx-serie server n tection rruption d 2 unit et 99 pair E n PMC I/O module 1 PMC I/O mudules)
-10.4" Color TFI LCD - Advanced preview - Dynamic graphic di - Fast ethernet / Data - Helical interpolatio - High speed skip fur - Manual handle free - Manual handle free - Number of tool offs ROBOT INTERFACI - Robot interface with (Hardware between - Robot interface with	control splay Only Lynx-serie splay Only Lynx-serie server n tection rruption d 2 unit et 99 pair E n PMC I/O module 1 PMC I/O mudules)

- Display unit 10.4" Color TFT LCD (except Lynx220M/300M)

FANUC 32i

Standard Specifications	
AXES CONTROL	
- Controlled axes	X, Z
- Simultaneous controlled axes	2 axes
- Axis control by PMC	
- Backlash compensation 0 ~ ± 9999	
 Backlash compensation for each ra traverse and cutting feed 	pid
- Controlled path	1 path
- HRV2 control	
- Inch / Metric conversion	
- Interlock All axes / ea	
 Least input command 0.001 / 0.0001 : 	mm/inch
- Mirror image	
- Servo off	
- Stored stroke check 1	
- Torque control	
 Unexpected disturbance torque detection 	function
OPERATION	
- Automatic operation(memory)	
- Buffer register	
- DNC Operation with Memory card	
 Handle incremental feed X1, X1 	0, X100
- Program restart	
INTERPOLATION FUNCTIONS	
- 1st. Reference position return Manu	
 2nd. reference position return 	G30
- Circular interpolation	G02
- Continuous threading	
- Dwell (per sec)	G04
- Linear interpolation	G01
- Positioning	G00
- Reference position return check	G27

- Thread cutting / Synchronous cutting

- Automatic acceleration / deceleration

- Jog feed override (10% unit) 0-2000 mm/min

0 - 200 %

FEED FUNCTION

- Cutting feedrate clamp - Feed per revolution
- Feedrate override (10% unit)

- Constant surface speed co	ntrol
- M - code function	M3 digits
- Spindle orientation	
PROGRAM INPUT	
- Absolute/incremental prog	gramming
- Automatic coordinate syst	em setting
- Canned cycle for drilling /	
- Canned cycle	
- Circular interpolation by R	programming
- Coordinate system setting	G50
- Coordinate system shift	
- Custom macro	
- Decimal point programmin	ng/
Pocket calculator type dec	imal point
programming	
- Diameter/radius programm	
- Direct drawing dimension	programming
- G code system A	
- G code system B/C	
- Input unit 10 time multiply	7
- Macro executor	
- Maximum program dimen	
- Multiple repetitive canned	
 Multiple repetitive canned Optional block skip 	
- Optional block skip - Plane selection	9 pieces G17, G18, G19
- Program file name - Programmable data input	32 characters G10
- Programmable data input - Sequence number	N8 digi
- Sequence number - SUB program call	10 folds nested

- Automatic tool offset

- Tool life management

- Tool nose radius compensation

- Direct input of offset value measured B
- T - code function T2 + 2 di

EDITING OPERATION Extended part program editing Number of registered programs 500 ea Part program editing Part program storage length 640 (256 KB)m SETTING AND DISPLAY
- Extended part program editing - Number of registered programs 500 ea - Part program editing - Part program storage length 640 (256 KB) m
- Extended part program editing - Number of registered programs 500 ea - Part program editing - Part program storage length 640 (256 KB) m
- Number of registered programs 500 ea - Part program editing - Part program storage length 640 (256 KB) m
- Part program editing - Part program storage length 640 (256 KB) m
- Part program storage length 640 (256 KB) m
SETTING AND DISPLAY
- Actual cutting feedrate display
- Alarm history display
- Display of spindle speed and T code at all screens
- Operation history display
- Operating monitor screen
- Parameter setting and display
- Periodic maintenance screen
 Program comment display 31 characters
- Run hours / part count display
- Self-diagnosis function
- Servo waveform display
- Spindle setting screen
OTHERS
- Cycle start and lamp
- Display unit 10.4" Color TFT LCD
- Feed hold and lamp
- NC and servo ready
- PMC system 32i-PMC
- Reset / rewind
OPERATION GUIDANCE FUNCTION
- EZ Guidei (Conversational Programming Solution)
INTERFACE FUNCTION
- Ethernet function Embedded ethernet

Optional Specifications

- Stored pitch error compensation - Stored stroke 2 and 3

- Stroke limit check before move

AXIS CONTROL

G43, G44, G49

OPERATION

 Active block cance 	1
	r/puncher interface is required
- Manual handle int	erruption
- Manual intervention	on and return
- Reference position	shift
INTERPOLATION :	FUNCTIONS
- 3rd / 4th reference	point reurn
- Circular threading	
 Multi step skip 	
PROGRAM INPU	Т
- Addition of workpie	ce coordinate system pair 48 pair
- Additional macro va	#100 ~ #199 #500 ~ #999
- Automatic corner of	
- Chamfering on/off	
- Interruption type c	ustom macro
	oft operator's panel) 9 piece
- Work coordinate s	ystem preset
TOOL FUNCTION /	TOOL COMPENSATI
- Addition of tool pairs	for tool life management
	128 pair
- Tool Load Monitor	
 Tool offset pairs 9 	9 / 200 / 400 / 999 pair
EDITING OPERAT	ION
- Number of register	
program storage le	
	1280M(512KB)_1000 e
	2560M(1MB)_1000 e
	5120M(2MB) 1000 e
DATA INPUT/OUT	PUT
- DNC1 control	
 External data inpu 	
- Fast ethernet / Da	ta server
- Remote buffer	
OTHERS	
- High speed skip fu	nction
- Manual handle int	erruption
- Stored pitch error	





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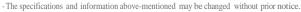
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